

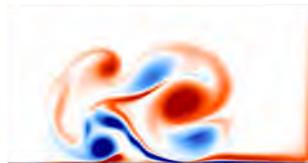
# Robust Optimization: application to rapid compression machines

F. Contino, P. Tsirikoglou, S. Abraham, G. Ghorbaniasl

The following slides were presented during the 2-day meeting organised at Politecnico di Milano the 22-23 of February 2018. If you have any question, don't hesitate to contact me by email ([fcontino@vub.ac.be](mailto:fcontino@vub.ac.be)). You can also find more information about the Euforia framework on the following website: <http://euforia-web.eu/>

## Robust Optimization: application to rapid compression machines

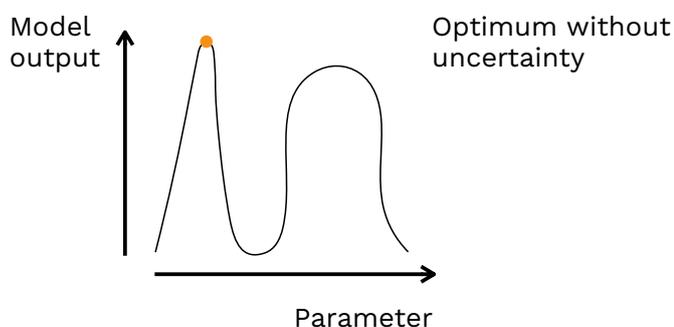
Francesco Contino  
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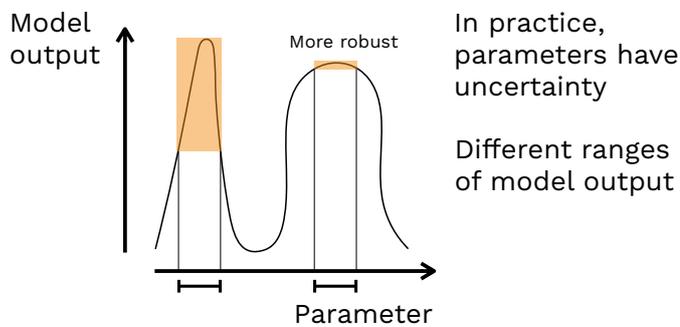
22/2/2018

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Deterministic optimization only gives the optimum of the model



## Robust optimization takes uncertainty into account



When taking uncertainty for the parameter, the range of output of the model can be large in the region of the optimum. This means that the average across the uncertainty might be higher elsewhere.

## Challenge of robust optimization: curse of dimensionality

The curse of dimensionality is the major challenge of robust optimization. We combine the cost of uncertainty quantification and the cost of optimization.

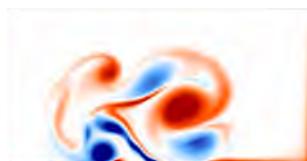
$$\text{Cost robust optimization} = \text{Cost UQ} \times \text{Cost optimization}$$

## Robust Optimization: application to rapid compression machines

Rapid Compression Machines

Euforia network

Robust optimization results



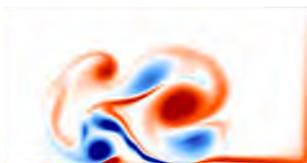
# Robust Optimization: application to rapid compression machines

## Rapid Compression Machines

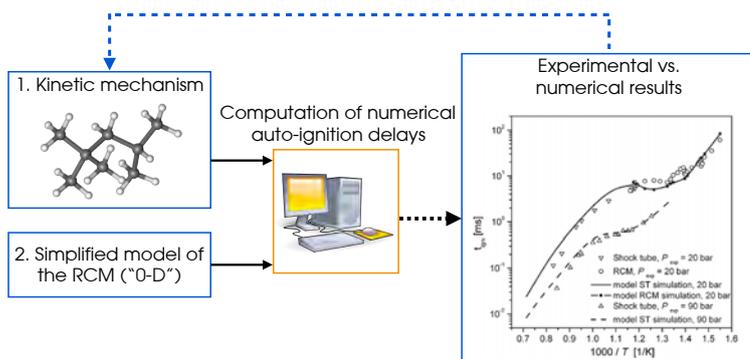
Working principles  
Why optimizing it?

Euforia network

Robust optimization results

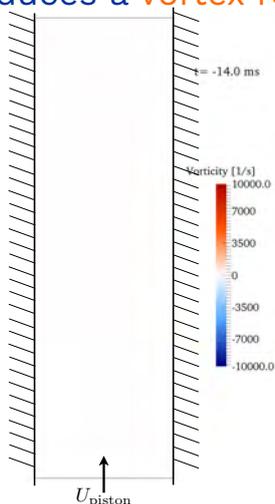


## Experimental data used to validate chemical kinetic mechanisms

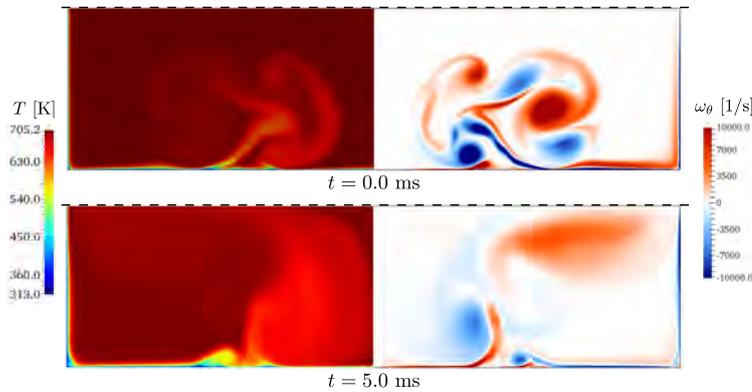


The 0-D model makes an intrinsic part of the validation process used by the researchers.

## Flat piston induces a vortex roll-up

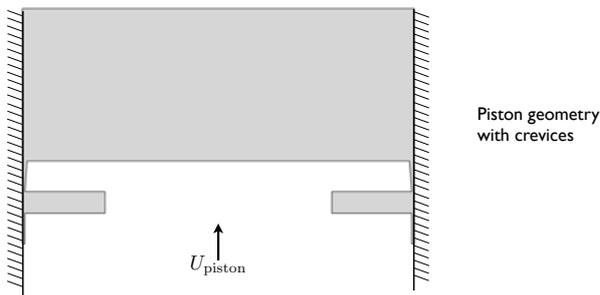


Flat piston induces a vortex roll-up and inhomogeneous temperature



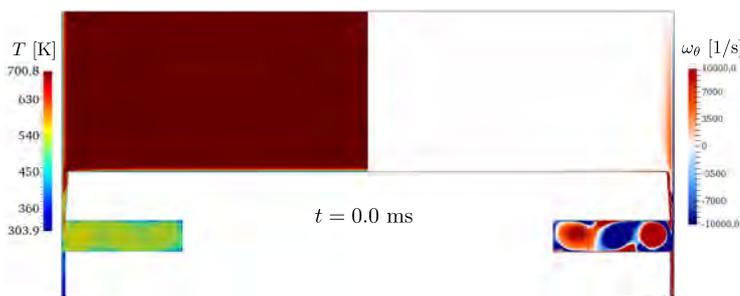
The vortex roll-up comes from the vorticity present at the wall and being scraped by the piston.

To prevent vortex roll-up, piston designed with crevices



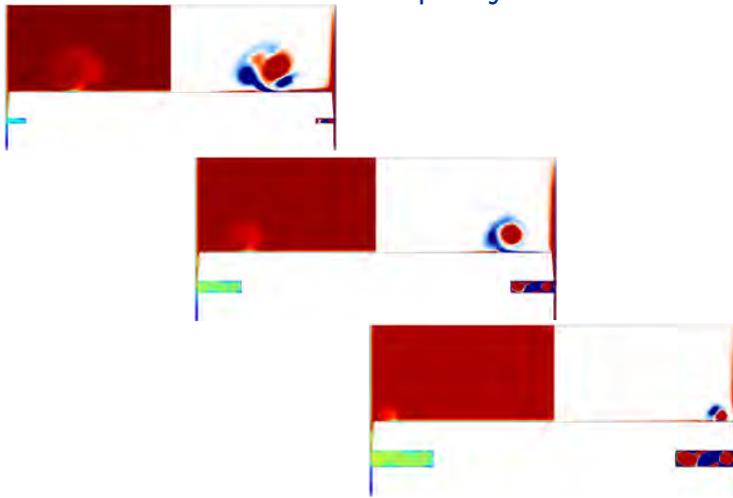
All RCMs implement crevices (instead of a flat piston) to absorb this vorticity.

With crevices, the temperature field is uniform



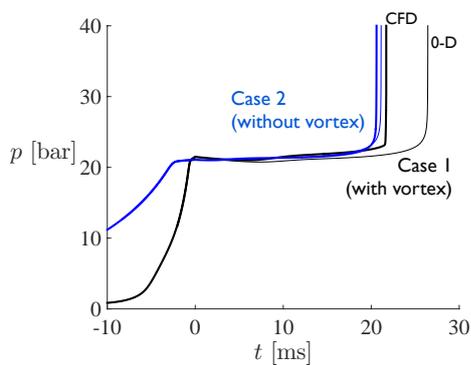
Thanks to the crevice, the temperature field is homogeneous.

All crevices are not equally efficient



One of the biggest problems for experimentalist is that the presence of crevices does not guarantee the absence of vortex roll-up.

The vortex roll-up induces significant deviation from the 0-D model



Crevices should be adequately designed otherwise experiments with and without badly designed crevices might not highlight the right problem.

Objective of the optimization: no vortex while being adiabatic

Crevices big enough  
but compression ratio fixed ( $r_v = 17$ )

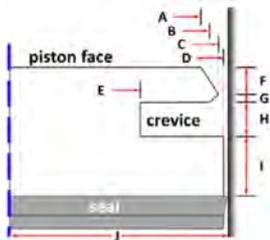
Adiabatic core big enough  
but risk of vortex due to speed

Objective: non-dimensional speed

$$obj = \frac{U_{vortex} \cdot t_{compression}}{L_{stroke}}$$

The main objective of the optimization is therefore not to have a vortex. But obviously, it should also have a fast compression to keep an adiabatic core.

## We optimize the geometry and the compression stroke properties



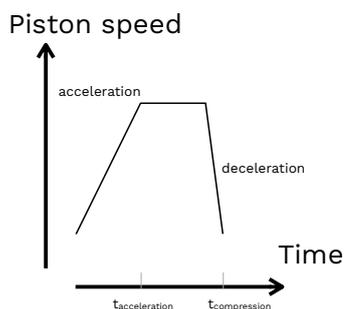
Goldsborough et al., 2017

Geometric parameters to be optimized

Geometrical uncertainty: 1%

To find the best objective, we will investigate different geometries, using the parametrization of Goldsborough et al. (PECS, 2017)

## We optimize the geometry and the compression stroke properties



Stroke profile based on three steps

Three opt. parameters: acceleration, deceleration,  $t_{\text{acceleration}}/t_{\text{compression}}$

Stroke length optimized with comp. ratio constant

Stroke uncertainty: 10%

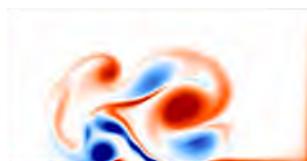
Aside from the geometry, one of the important features is the compression stroke. We have parametrized it using three main steps: acceleration, constant speed, and braking. While the uncertainty for the geometry was 1%, the uncertainty on the stroke is much higher (often not being measured accurately): 10%.

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Rapid Compression Machines

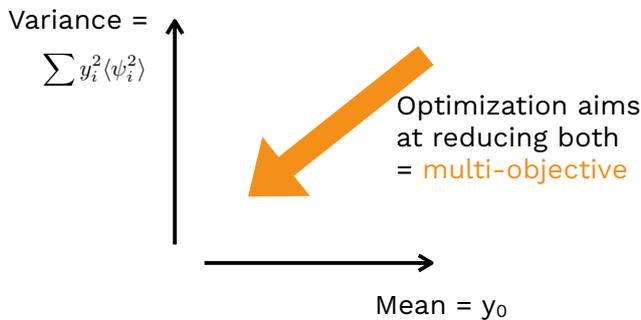
Euforia network  
Uncertainty Quantification  
Optimization methodology

Robust optimization results





## Mean and variance of the objective are given directly by Polynomial Chaos



The advantages of polynomial chaos are the faster convergence compared to methods such as Monte Carlo, and the easy recovery of the mean and variance based on the coefficients of the polynomials.

## Optimization based on Cuckoo search coupled with specific sorting criterion

**Cuckoo search:** mimics cuckoos flying around to lay eggs

Survival of eggs in good nests = good model solution

Fly following Levy distribution = many small steps for every big one

Non-dominated  
Sorting by crowding distance (from NSGA-II)

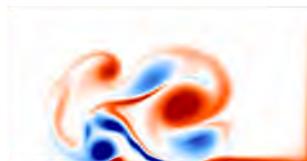
We used one of the available optimizers, namely Cuckoo search. It is based on the (aggressive) breeding behavior of the Cuckoo birds and the foraging path of animals. They fly using a Levy distribution which includes many small steps (for local exploration) for every big step (for global exploration).

## Robust Optimization: application to rapid compression machines

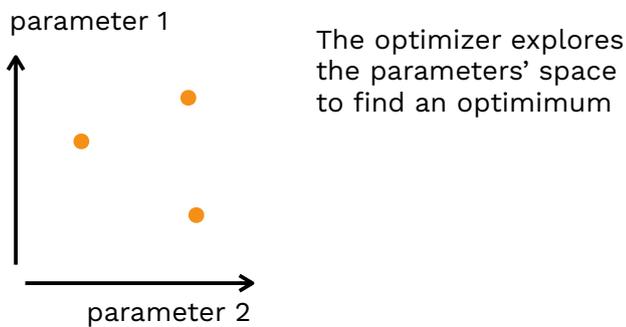
Rapid Compression Machines

Euforia network

Robust optimization results  
Computational cost  
Pareto front

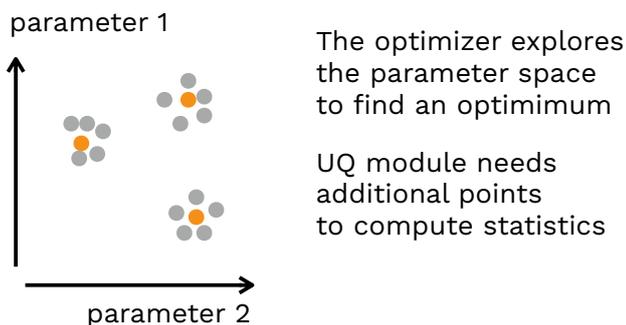


## The total cost includes the sampling for optimization and UQ



While the optimizer search for the optimum in the parameters' space, it requires statistics (mean and variance) as multi-objective

## The total cost includes the sampling for optimization and UQ



These statistics are provided by sampling in the region of the sample using the polynomial chaos. Sampling based on Sobol sequence. S. Abraham et al., JCP, 2017.

## For this reference case, the cost is still very expensive

Full polynomial chaos order 2, 9 uncertain parameters requires 110 samples

Optimization is based on full CFD model for all samples

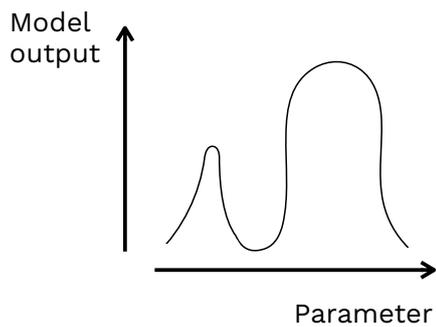
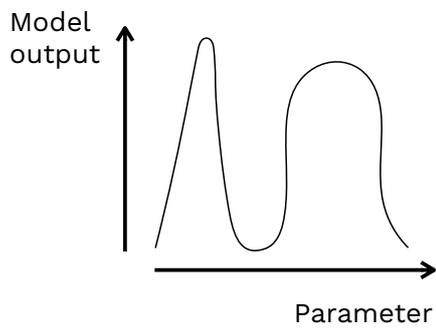
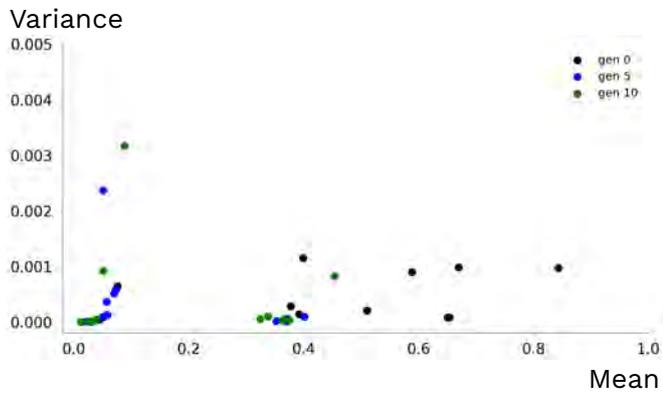
Around 10 000 CFD simulations on 60 cores: 2 days

This will be the reference for future research (see perspectives)

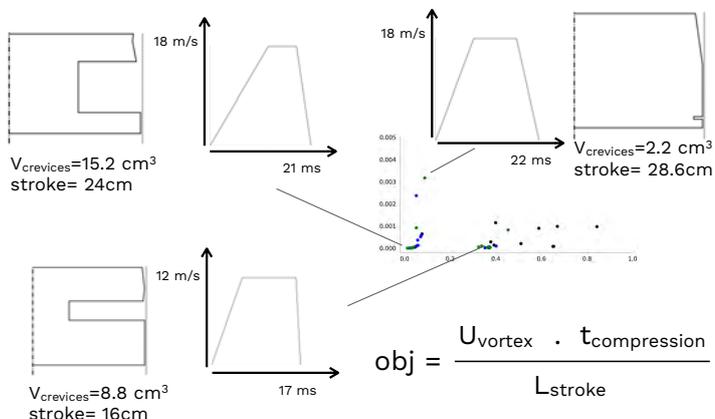
We use this case as a demonstration for more advanced techniques to reduce the computation cost. Therefore, the current simulations were based on full polynomial chaos and CFD for every sample.

### Variance and mean are non-confronting objectives

Reducing the mean also helps reducing the variance of the objective.



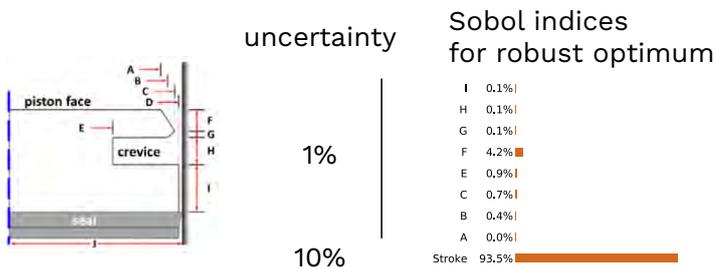
### Variance and mean are non-confronting objectives



Here are some geometries and compression stroke properties corresponding to some points in the objective space.

### Using Sobol indices, we compute the sensitivity of the variance

Sobol indices are readily available as a side-product of polynomial chaos. It measures the contribution of each parameter to the variance.

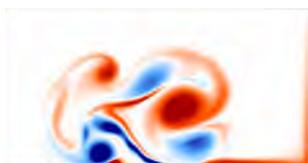


### Robust Optimization: application to rapid compression machines

Rapid Compression Machines

Euforia network

Robust optimization results



Next step for **this RCM study**

Use as reference to further illustrate:

1. Surrogate-based optimization  
No need to run CFD for all samples  
Expected speed-up: **~10**

2. Sparse Polynomial Chaos  
Take advantage of sparsity  
to reduce number of samples  
Expected speed-up: **~2**  
Abraham et al., JCP, 2017

Next step for **robust optimization**

Application to Diesel case

In collaboration with  
ICE group @PoliMi

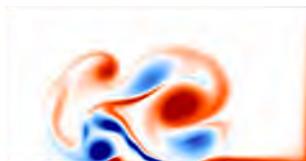
Tier-1 cluster for 3  $10^6$  core.hours

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## Current Contributors to OpenFOAM

OpenFOAM is developed by a team of individuals who contribute their work to the project, with the support and consent of the companies that employ them. Contributions are made under the OpenFOAM Contributor Agreement (to facilitate enforcement of the free, open source license), signed either by the individual, or by the organisation that employs them.

### Principal Contributors

- **Henry Weller, CFD Direct (UK)**: creator of FOAM and co-founder of OpenFOAM, and its architect and core developer, who maintains the public **OpenFOAM development repository**.
- **Chris Greenhalghs, CFD Direct**: co-founder and manager of OpenFOAM who maintains the website, **OpenFOAM releases** and free **OpenFOAM documentation**.
- **Bruno Santos, InueCAPE (Portugal)**: active maintainer of OpenFOAM who manages issues on the **OpenFOAM Issue Tracking system**.
- **Will Bainbridge, CFD Direct**: full-time core developer of OpenFOAM.
- **Mattijs Janssens (individual, UK)**: co-founder of OpenFOAM, and developer of major functionality, notably **snappyHexMesh**.

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- **Juha Peltola, VTT Technical Research Centre of Finland Ltd.**
- **Timo Niemelä, VTT Technical Research Centre of Finland Ltd.**
- **Ronald Oertel, HZDR (Germany)**.



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2. Quasi-steady state stiffness removal